IN THE SPECIFICATION

Please replace the paragraph from page 22, line 15 to page 23, line 1, with the following amended paragraph:

Immediately after the ultrasonic motor 10 starts rotating (if YES at step S59), <u>the initial driving frequency is set as the current starting frequency (step S68), and</u> the current rotational speed of the ultrasonic motor 10 is determined from a variation in the value of the counter 20b within a predetermined amount of time (step S69). Subsequently the determined current rotational speed is stored in the EEPROM 23 (step S71), and it is determined whether the variable n is greater than zero (step S73). If the variable n is greater than zero (if YES at step S73), the previously detected ambient temperature and the current detected ambient temperature are read out of the EEPROM 23 to determine whether the difference between the absolute value of the previous speed and the absolute value of the current speed is equal to or greater than a predetermined value (CONST) (step S75). If the above-mentioned difference is equal to or greater than the predetermined value (if YES at step S75), this means that the load acting on the ultrasonic motor 10 has varied substantially. In this case, it is possible that the resonance frequency of the ultrasonic motor 10 may vary substantially. Accordingly, if the above-mentioned difference is equal to or greater than the predetermined value (if YES at step S75), all the starting frequency data fs[n] stored in the EEPROM 23 are cleared (n=0) (step S65), and subsequently the current starting frequency fscur is set ~~to~~ <u>as</u> the maximum frequency in

the controllable frequency range (step S67). Thereafter, control proceeds to step S77. If

the variable n is equal to or smaller than zero (if NO at step S73) or if the

above-mentioned difference is smaller than the predetermined value (if NO at step S75),

control proceeds to step S77 since the previous data can be utilized. At step S77, a

starting frequency storing and average value calculating process ("STARTING

FREQUENCY STORING & AVERAGE VALUE CALCULATION" shown in Figure 5)

is performed, and control returns to the drive process shown in Figure 3.

Please replace the paragraph from page 28, line 13 to page 29, line 4, with the following amended paragraph:

Figures 11A and 11B are flow charts for the ultrasonic motor start process (USM Start Process) shown in Figure 10, and correspond to Figures 4A and 4B. In Figure 11A, steps S410, S450, S470, S490, S510 and S530 correspond to steps S41, S45, S47, S49, S51 and S53 of Figure 4A. Likewise, in Figure 11B, steps S570, S680, S590, S610, S630, S670, S690, S730, S750 and S770 correspond to steps S57, S59, S61, S63, S67, S68, S69, S73, S75 and S77 of Figure 4B. Only steps S430 and S550 of Figure 11A differ from Figure 4A, and only steps S650 and S710 differ from Figure 4B. In step S430, the detected ambient temperature is stored in the RAM 20c instead of the EEPROM 23. Furthermore, in steps S550 and S650, the starting frequency data is cleared from the RAM 20c instead of the EEPROM 23. In step S710, the determined rotational speed is stored in the RAM 20c instead of the EEPROM 23.

4

IN THE DRAWINGS

The attached sheets of drawings include changes to Figures 4B and 11B. These sheets, which include Figures 4B and 11B, replace the original sheet including Figures 4B and 11B. In Figures 4B and 11B, S68 and S680 have been added, respectively. Additionally, S67 and S670 have been revised, respectively. Each of the amendments is explained further in the remarks.